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7 **Eeeb344 Electromechanical Devices Chapter 7** fr = sfe This voltage is induced in a rotor containing both resistance and reactance. The rotor resistance R_r is a constant, independent of slip, while the rotor reactance is affected in a more complicated way by slip.

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EEEB344 Electromechanical Devices Chapter 5 7 The full equivalent circuit is shown below: A dc power source is supplying the rotor field circuit, which is modeled by the coil's inductance and resistance in series. In series with R_F is an adjustable resistor R_{adj} which controls the flow of the field current.

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EEEEB344 Electromechanical Devices Chapter 4 2 1. A simple loop in a uniform magnetic field The figure below shows a simple rotating loop in a uniform magnetic field. (a) is the front view and (b) is the view of the coil. The rotating part is called the rotor, and the stationary part is called the stator.

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The technologies considered include: the brushed motor (Chapter 5), brushless motors (Chapter 6), vector controlled induction motors (Chapter 7), and the step-per motor (Chapter 8). In addition a of motor-drives fall outside this rather ar-bitrary classi?cation system, and these are considered in Chapter ...

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Principles of Electromechanical Systems 5 10 m 7.84 kNm kg 9.8 N = 80 kg $\times \times = W = Fr$ A newton-meter is a joule $W = 7.84 \text{ kJ}$ To calculate the power, use Equation (16.6) s J 261.33 30s 7.84 kJ $P = = 16.3$ ELECTRICAL POWER 16.3.1 Sinusoidal Power Equation We knew from the previous section that t W

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ELECTROMECHANICAL DYNAMICS, PART I: DISCRETE SYSTEMS This manual presents in an informal format solutions to the problems found at the ends of chapters in Part I of the book, Electromechanical Dynamics. It is intended as an aid for instructors, and in special circumstances for use by students.

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