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# **Le Api Robot Volume 4**

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2. When the subscript  $i$  for injection, injected, or irreducible is used, it should appear first in subscript order (but after  $r$  for relative'). Examples:  $B_{ig}$ , formation volume factor of injected gas, and  $c_{ig}$ , compressibility of injected gas. 3. Except for Cases 1 and 2 above (and symbols  $k_h$  and  $L_v$ ), phase, composition, and system sub-

du 10 juin 1977 et résolutions adoptées à la quatrième session]. Adopté à Genève le 8 juin 1977 Textes authentiques : anglais, arabe, chinois, espagnol, français et russe. Enregistré par la Suisse le 23 janvier 1979.

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from the API, which amounts to virtually all the declaring code needed to call up hundreds of different tasks. Those 11,500 lines, however, are only 0.4 percent of the entire API at issue, which consists of 2.86 million total lines. In considering “the amount and substantiality of

2/4/2015 · one robot radius). Detection of a wheel drop (on any wheel). Charger plugged in and powered. Should one of the above safety-related conditions occur while the OI is in Safe mode, Roomba stops all motors and reverts to the Passive mode. If no commands are sent to the OI when in Safe mode, Roomba waits with all motors

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Step 4: Set up a UDP server on the PC, Mac, or mobile device and check the message from IP 0.0.0.0 via UDP PORT 11111. Step 5: Send “streamon” to the Tello via UDP PORT 8889 to start streaming. Steps 1 and 2 must be completed before

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attempting step 5. Tello Command Types and Results The Tello SDK includes three basic command types.

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Journal of Field Robotics (JFR), Vol. 34,  
No. 2, pp. 381 – 399, March 2017. Details.  
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Jim Mainprice, Rafi Hayne, and Dmitry  
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